



Taiwan Ocean Radar Observing System (TOROS)

Presented by Dr. Ming-Chih CHENG, NAR Labs
for

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Founded in 2008. Research and innovation platform of Marine Science and Technology. Missions:

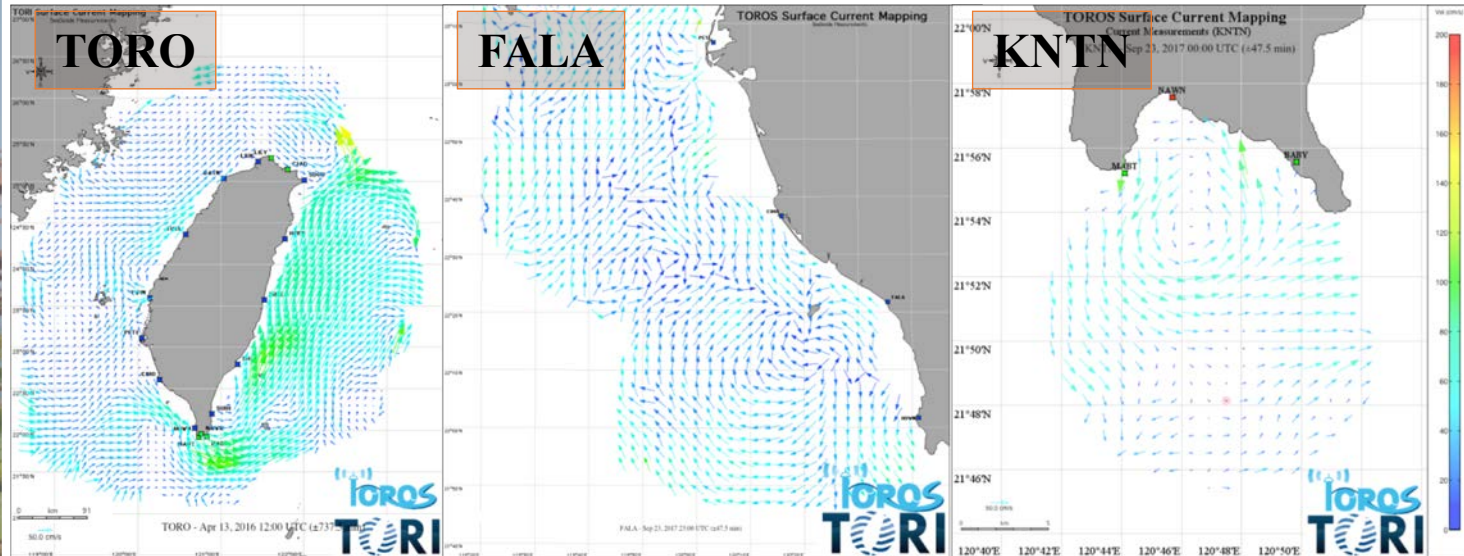
- Establish marine technology and ocean science research platforms
- Operate and maintain of ocean research vessel
- Support and enhance national marine technology and ocean science researches
- Promote and motivate cutting-edge ocean researches
- Foster ocean research personnel



Taiwan Ocean Radar Observing System (TOROS)



Products	Mesh Grid	Area	Since
TORO	10 km × 10 km	Half of Taiwanese EEZ	Nov. 2012~
FALA	4 km × 4 km	South Taiwan Strait	May 2016~
KNTN	1 km × 1 km	Nanwan Bay	Sep. 2014~

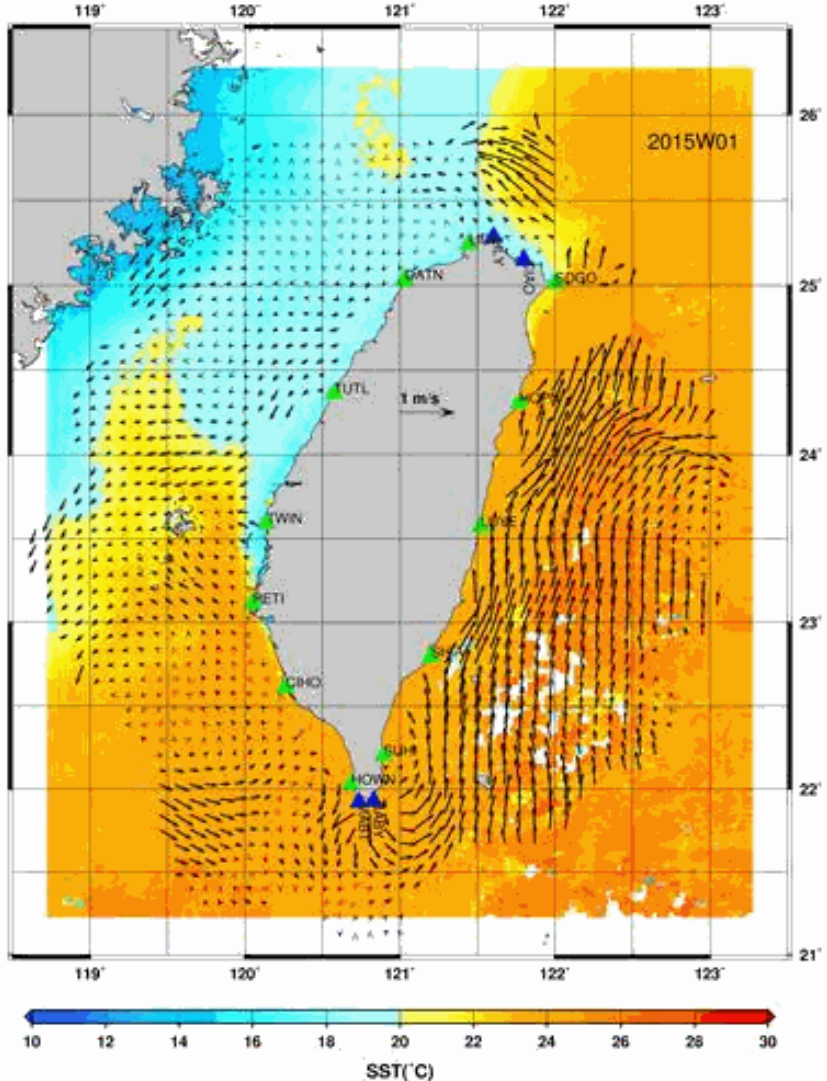


TOROS A compact type ocean radar system surrounding Taiwan

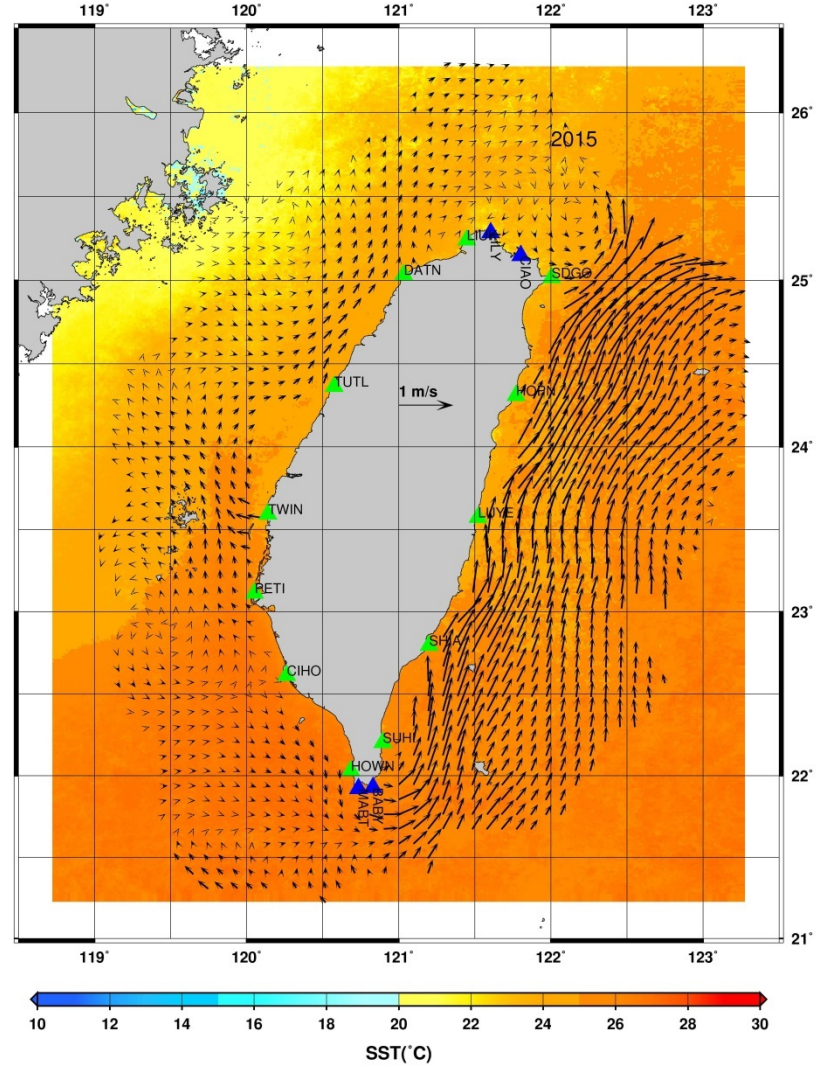
SST (Sea Surface Temp.) & SSC (SS Current)



Weekly mean SST and SSC



Annual mean of SST and SSC



International & Domestic Cooperation

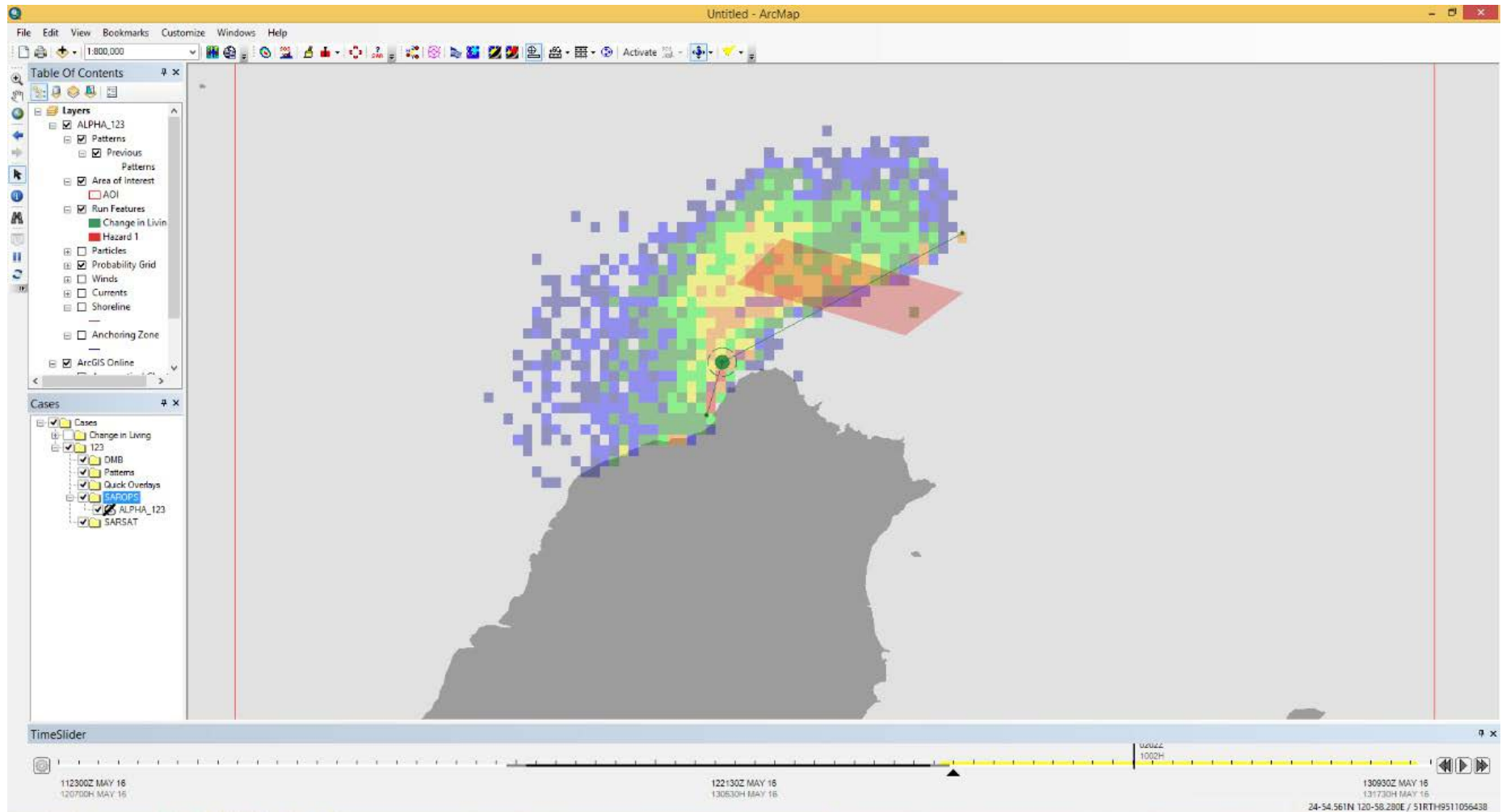


No.	Topics & Resources	Association
1	Domestic Marine Affairs - Search and Rescue based on HFR surface current - Marine Pollution Response based on HFR surface current - Ship Detection based on HFR backscatter	CGA ¹² EPA ¹ Navy ¹²³
2	East China Sea Joint Research Flux and Ekman transmission Taiwan : TOROS ocean radar network, sbADCP on TaiMa Star Japan : Yonaguni ocean radar, R/V	TORI Kyushu Univ. ^{13*} Nagoya Univ. ^{3*} Ryukyu Univ. ¹ NCKU ¹³ Central Police Univ. ¹
3	Kuroshio Research Kuroshio Flux and its variation Taiwan : TOROS ocean radar network, R/V OR1, R/V OR3 USA : R/V Roger Revelle	TORI WHOI ^{13*} APL ^{13*} IONTU ¹²³ NSYSU ¹²³
4	NANWAN Coastal Marine Science Research Coral Spawning and Cold water intrusion TORI : TOROS ocean radar network Taiwan : Water Resources Agency, NCKU	TORI WRA ¹ NCKU ¹²³
5	Luzon Strait Ocean Observing System Kuroshio and Internal Waves Observation, HF radar R&D Taiwan : 2 Phase Array Radars, R/V Philippines : 3 Phase Array Radars, R/V	TORI Univ. Philippines ^{123*} WHOI ^{123*} Univ. Hawaii ^{123*} NCU ^{23*}

1 Data Supply 2 Knowledge and Technology supply 3 Technology Development Cooperation

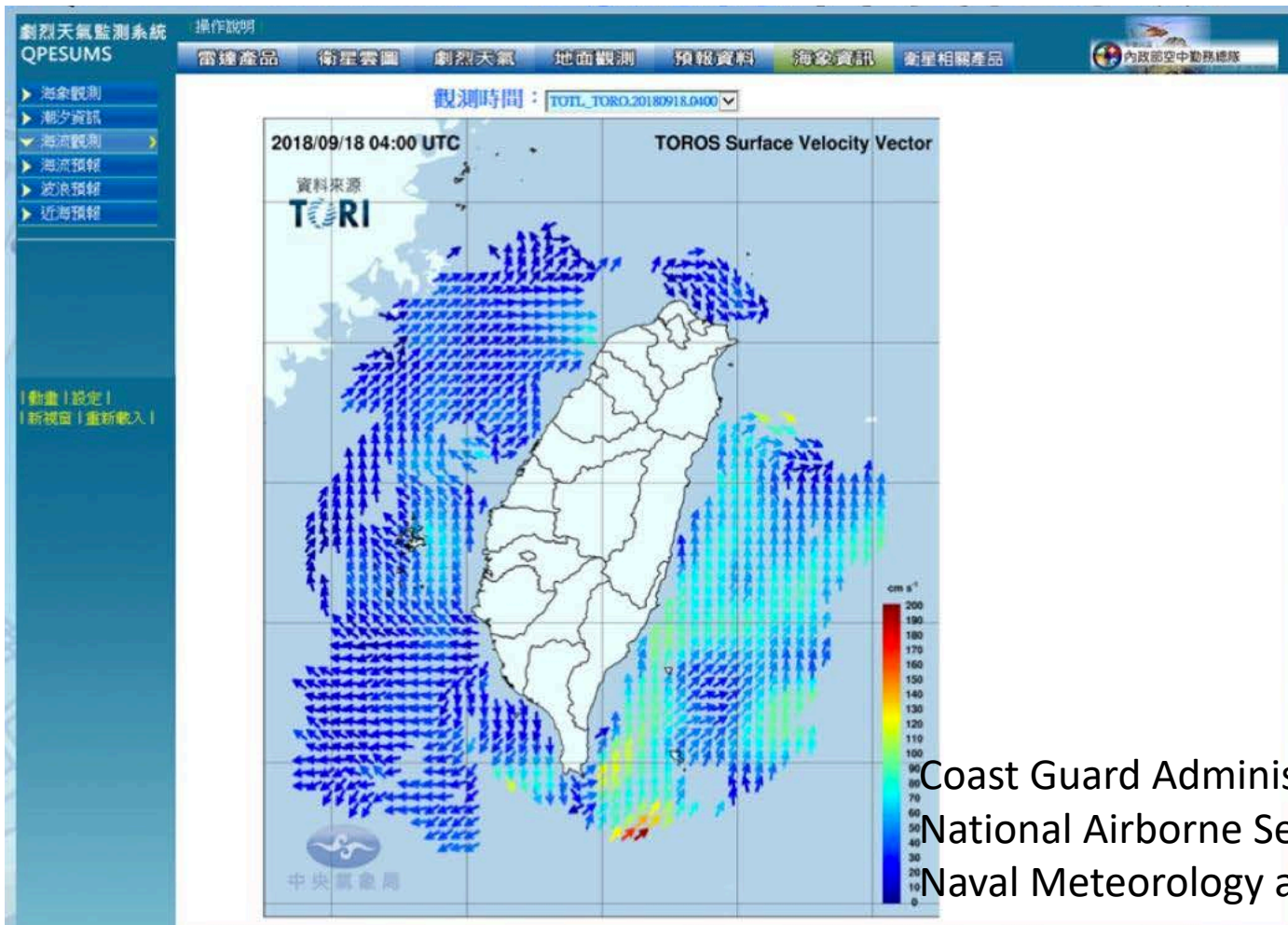
* MOU signed

Search and Rescue objects drifting assessment by SARMAP with HFR surface current data



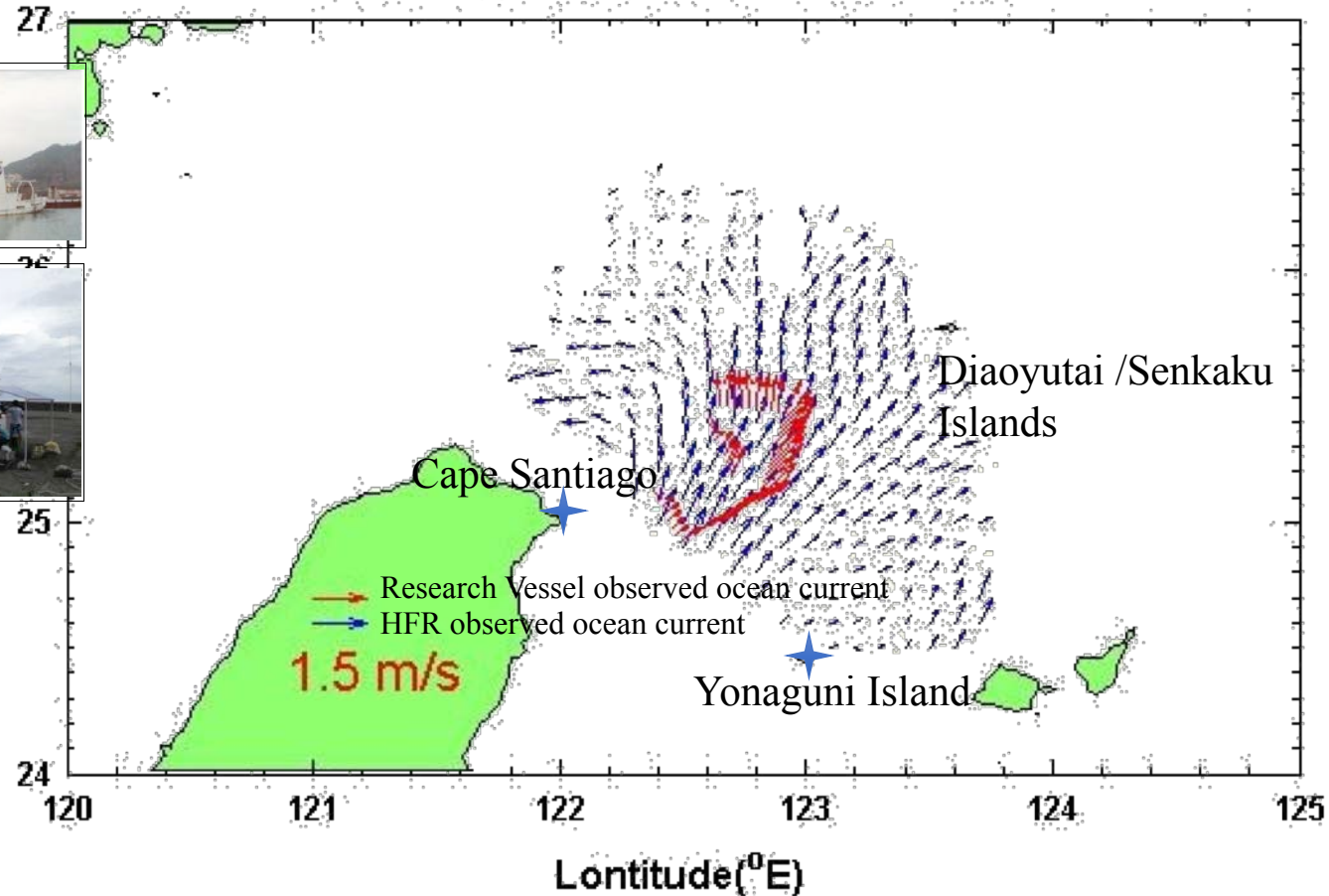
QPESUMS for CGA, NASC and Naval METOC

(Quantitative Precipitation Estimation and Segregation Using Multiple Sensor)

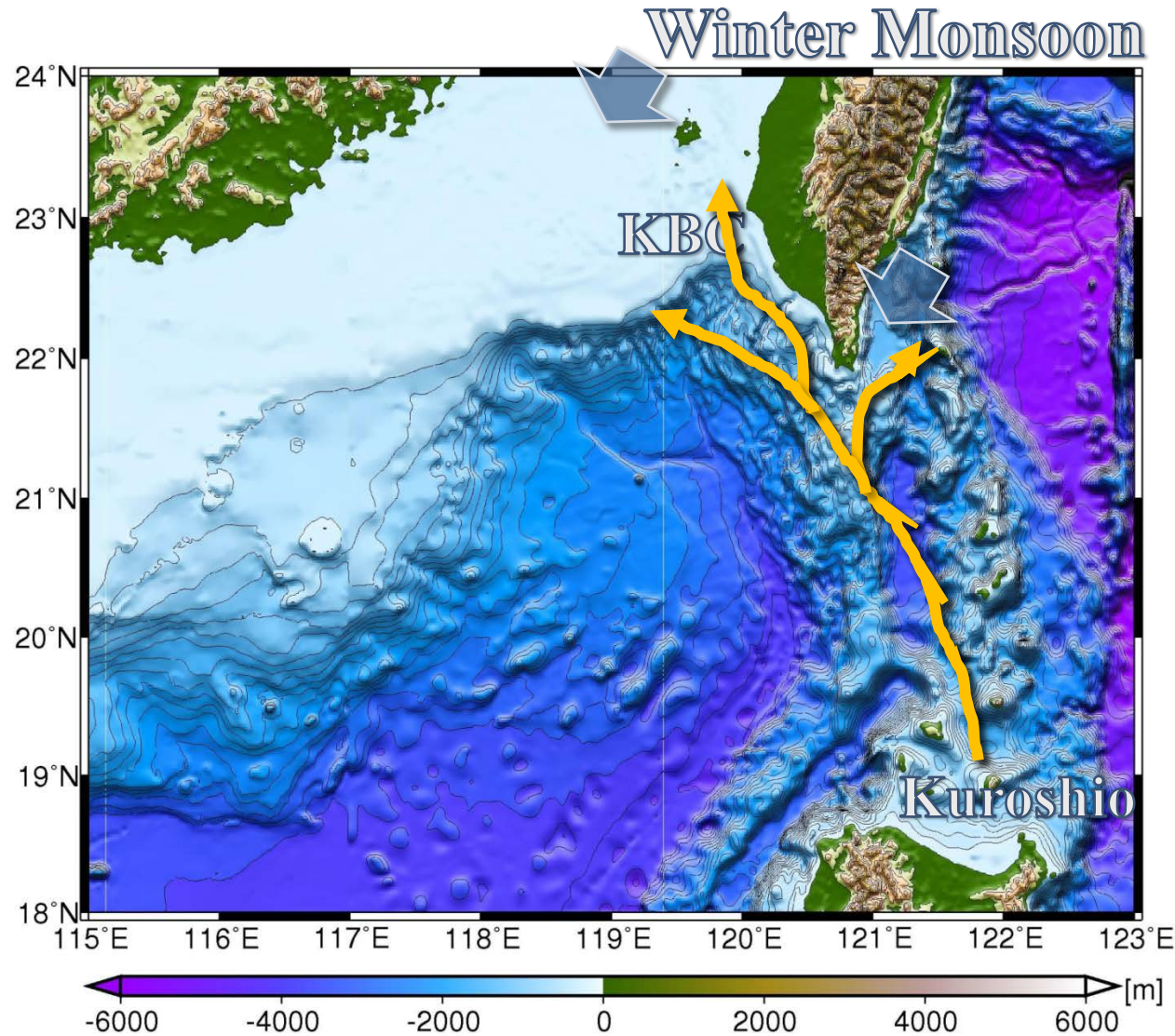
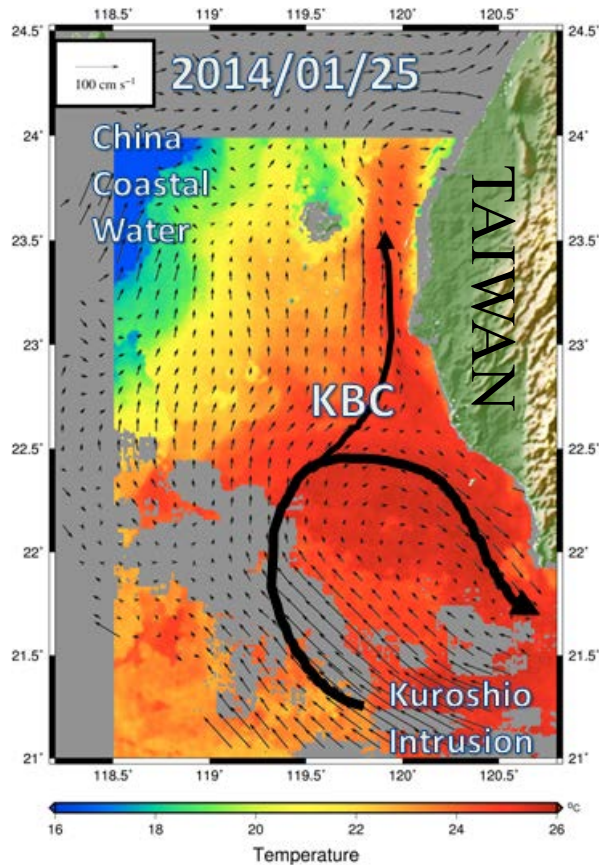


Japan and Taiwan

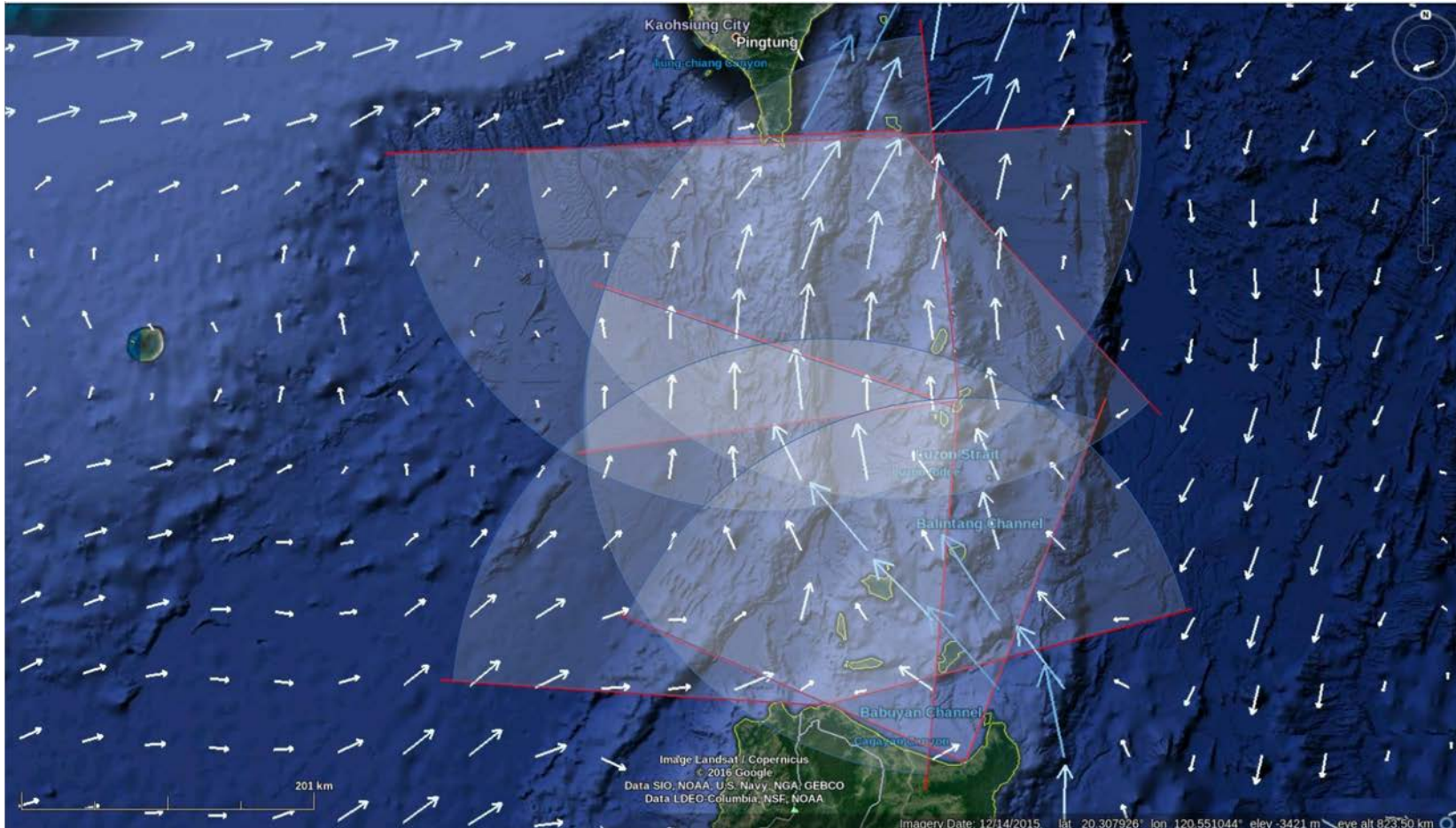
GMT Time: 2012-06-14-0000 ~ 2012-06-16-2300



Taiwan and US



Luzon Strait Ocean Observing System



Plan to Show Surface Current Maps on GEO HF Radar Network



Global HF Radar Network

Established at the GEO-VIII Plenary in Istanbul, Turkey; the Global High Frequency Radar Network is a vision for a global operational system measuring ocean surface currents to support monitoring of marine and coastal ecosystems.



- Home
- References/Reports
- GEO HF Radar Activities
- Network Members
- Contacts
- Meetings

Interactive Map of High Frequency Radar

This map shows all of the locations of the HF Radar sites all over the world.

Coming Soon...

« -1 Day -1 Hour 2018-09-21 00:00:00 from UTC +1 Hour +1 Day » [Bookmark View](#)

Control Panel

UTC: 2018-09-21 14:15:36
Local: 2018-09-21 22:15:36

Participants

Australia
[IMOS](#)

Canada
[OCEAN NETWORKS](#)

Croatia
[INSTITUTE OF OCEANOGRAPHY AND FISHERIES](#)

Germany
[GKSS INSTITUTE FOR COASTAL RESEARCH](#)

地圖 衛星檢視

North Pacific Ocean

North Atlantic Ocean

http://global-hfradar.org/

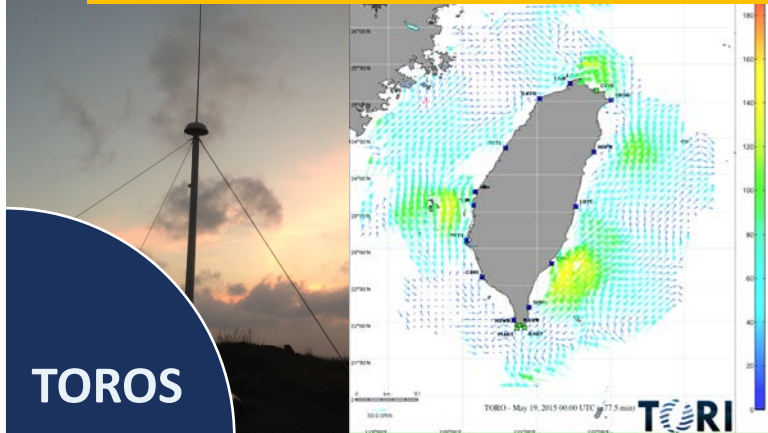
Offshore, deep sea, near real-time, long-term observations

Moored Ocean Observing System, Taiwan

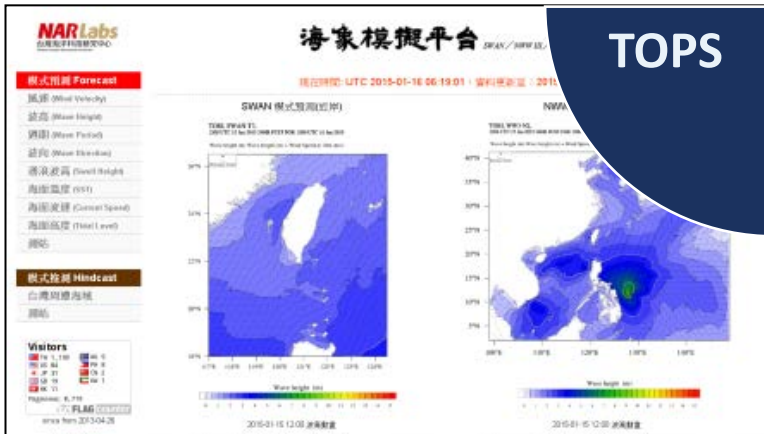


BUOY

Taiwan Ocean Radar Observing System



TOROS



TOPS

Taiwan Ocean Prediction System



LIDAR

Offshore Wind Speed Measurement

Research Vessel LEGEND

-Deep Sea Resources and Geo-hazard Explorer



L.O.A 75.97 m
Breadth.. 16 m
Draft.....5.6 m
GT..... 2,581

Speed max..... 12 kts
Cruising spd. 10 kts
Duration..... 30 days
Crew/Sci. Berth... 19/24

Keel Laying March 2016
Launch May 2017
Delivery November 2017
Operation ... 2018

LEGEND : Characteristics

■ Full-Depth Seafloor Mapping :

Deep Water : *Kongsberg* EM 122 (2 degree X 2 degree; up to 11000 m)

Shallow Water : *Kongsberg* EM 2040 (0.7 degree X 0.7 degree; < 600 m)

■ Sub-bottom Profiler : *Kongsberg* SBP120-3 (1-20 kHz; < 1 m vertical resolution)

■ ROV Survey and Seafloor Samplings :

Forum (Perry) Triton XLX ROV system (3000 m, 150 HP, 2 manipulators)

■ Coring : *KleyFrance* giant piston corer (12-15 m)

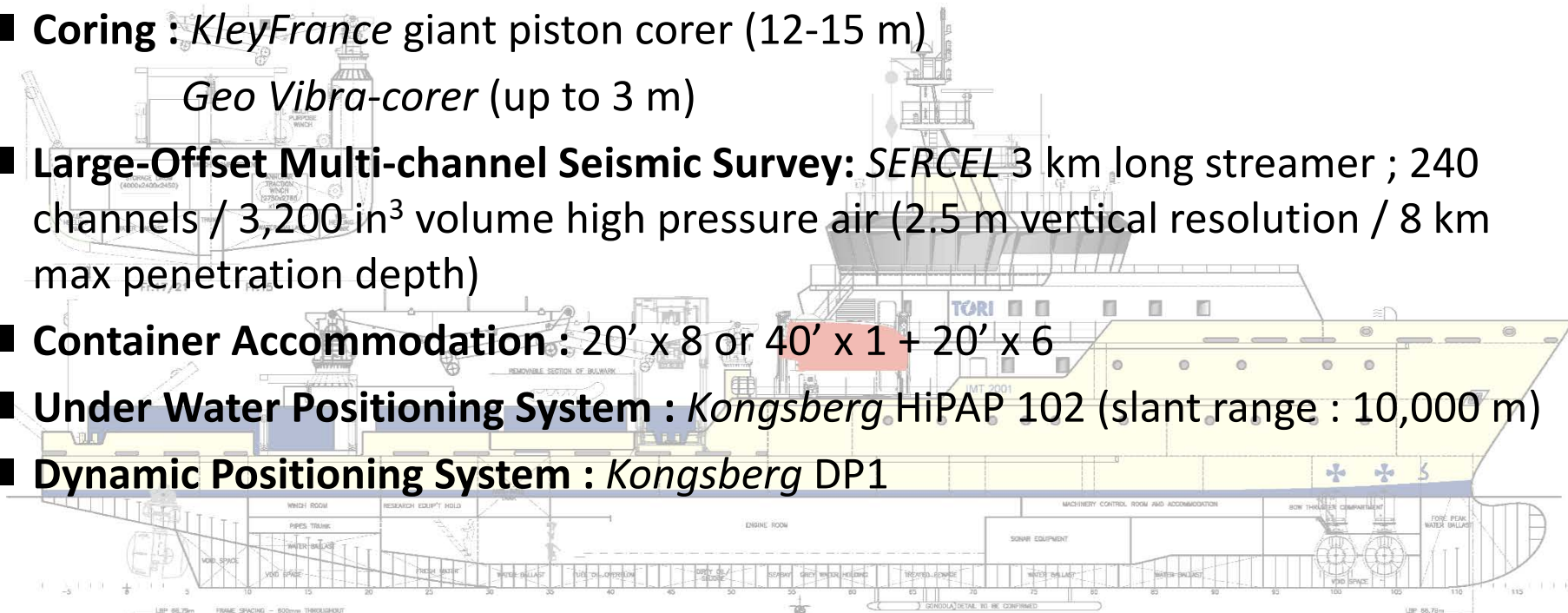
Geo Vibra-corer (up to 3 m)

■ Large-Offset Multi-channel Seismic Survey: *SERCEL* 3 km long streamer ; 240 channels / 3,200 in³ volume high pressure air (2.5 m vertical resolution / 8 km max penetration depth)

■ Container Accommodation : 20' x 8 or 40' x 1 + 20' x 6

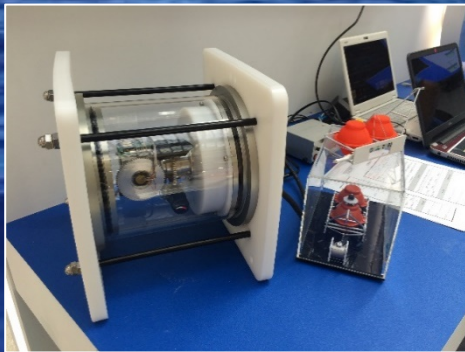
■ Under Water Positioning System : *Kongsberg* HiPAP 102 (slant range : 10,000 m)

■ Dynamic Positioning System : *Kongsberg* DP1

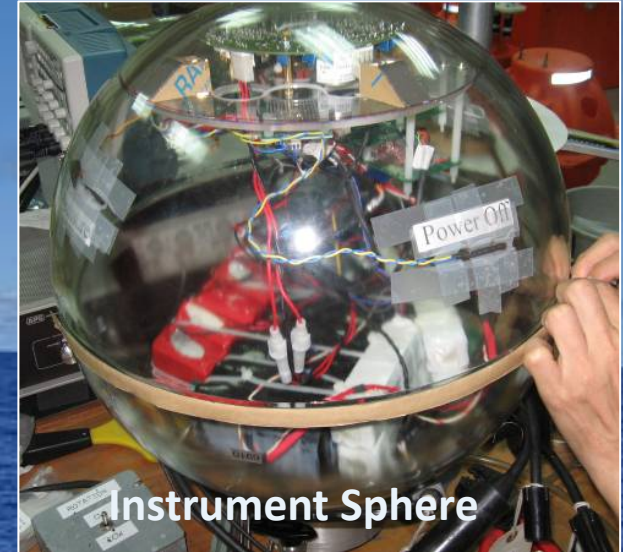
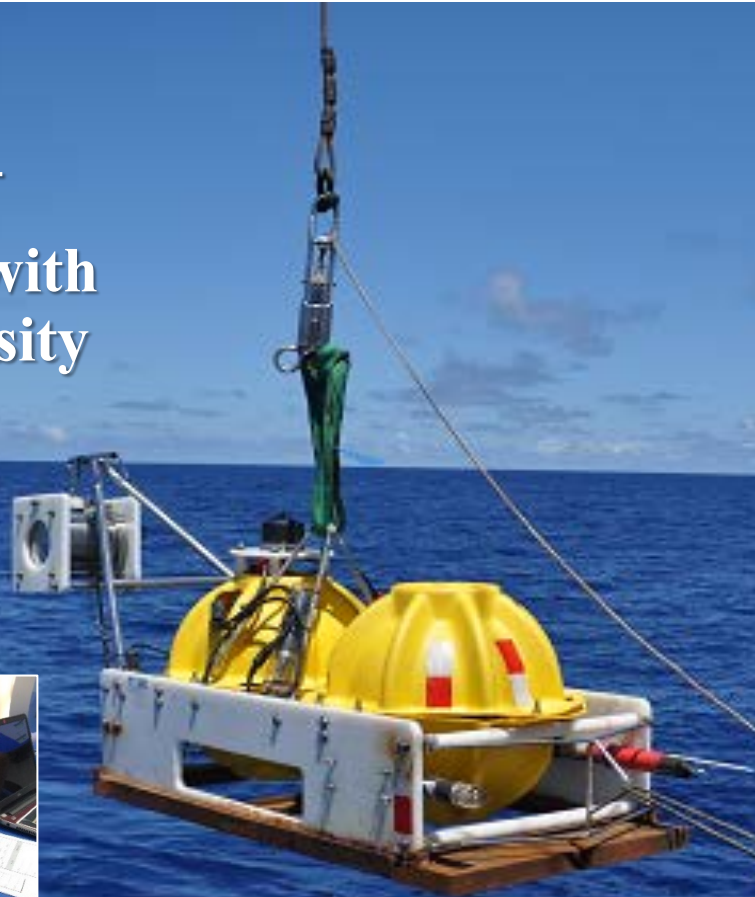


Ocean Bottom Seismometer (OBS)

- Since 2008
- # of OBS: 30+
- Cooperation with Tokyo University



Sensor with Auto Leveling



Instrument Sphere

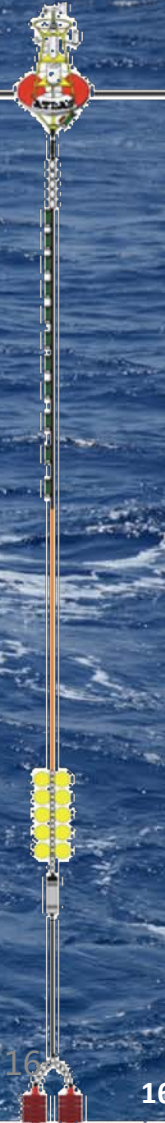
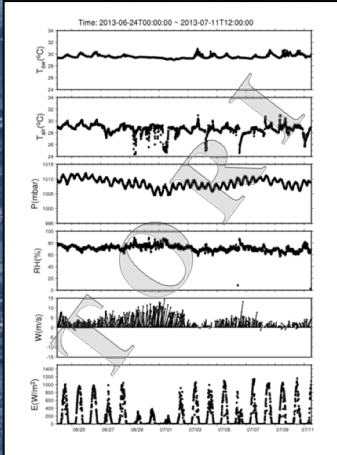
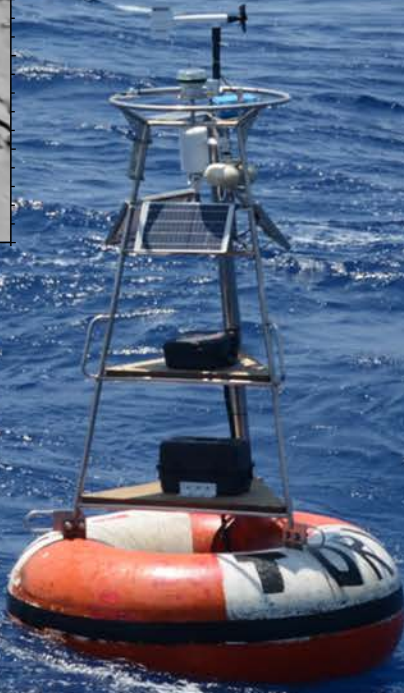
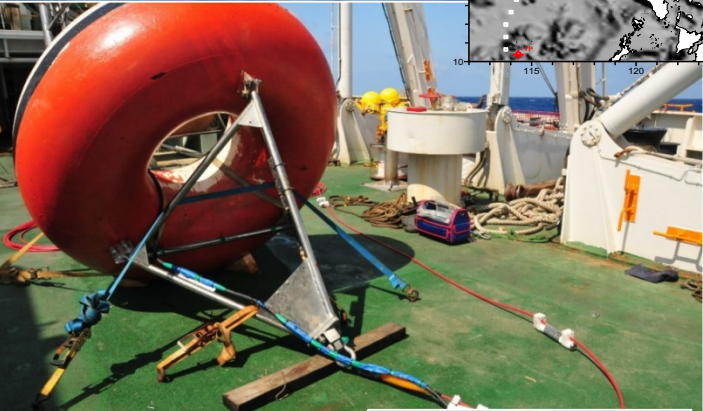
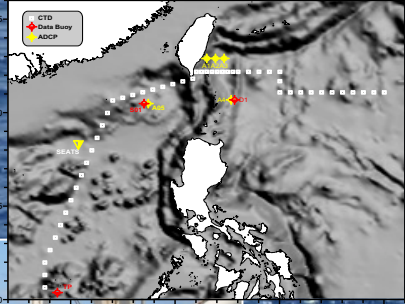
Maximum depth capability: 5,000meters

Near Real-Time Data Buoys



Near real-time, long-term ocean and atmosphere monitoring in open ocean by moorings.

- Air
Temperature,
Pressure,
Humidity,
Wind vector,
Solar radiation
- Water
Temperature,
Salinity



- Establish global partnerships and online platforms to pursuit "Global Excellence, Local Impact"
- Promote innovative R&D efforts and a range of international collaboration
- Share the technologies and experiences with international society
- Enhance the contribution of Earth observation database and integrate into global community



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